

T2: Applications of Polynomial Eigenvalue Decomposition to Multichannel Broadband Signal Processing Part 4: Speech Processing Applications

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Introduction

Speech signals captured by multiple microphones are increasingly common

- Broadband nature of speech
- Temporal correlations especially when there is reverberation

Processing approaches include

- Splitting broadband into multiple narrowband signals via FFT [Cohen2002; Markovich2009]
⇒ Ignores spectral coherence and correlations between frequency bands
- Classical subspace methods use the (instantaneous) spatial covariance matrix [Asano2000]
⇒ Inadequate for convolutively mixed and/or broadband signals

Promising Approach: Polynomial Matrix Eigenvalue Decomposition (PEVD)

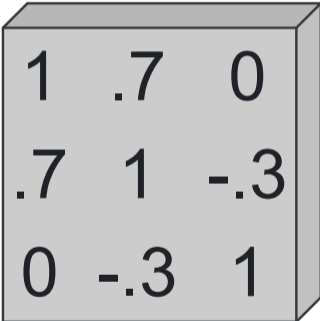
⇒ This Talk: Iterative Time-domain Algorithms e.g. SMD [Redif2015]

Recap: From EVD to PEVD

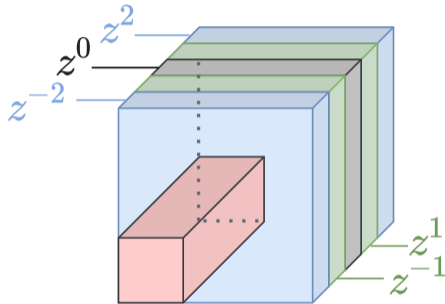
$\mathbf{R}(0)$

z^0

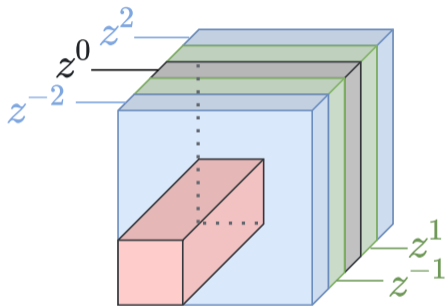
| | | |
|----|-----|-----|
| 1 | .7 | 0 |
| .7 | 1 | -.3 |
| 0 | -.3 | 1 |



Matrix example.

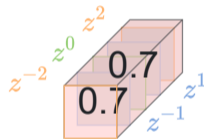


Polynomial matrix example.



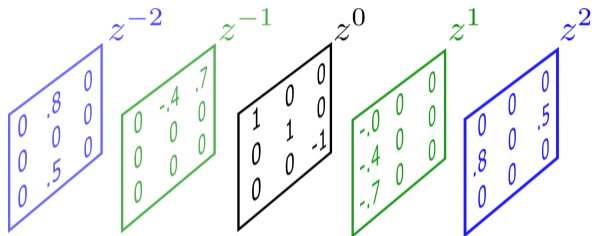
Polynomial with matrix coefficients.

$$r_{31}(z) = 0.7z^{-1} + 0.7z^1$$

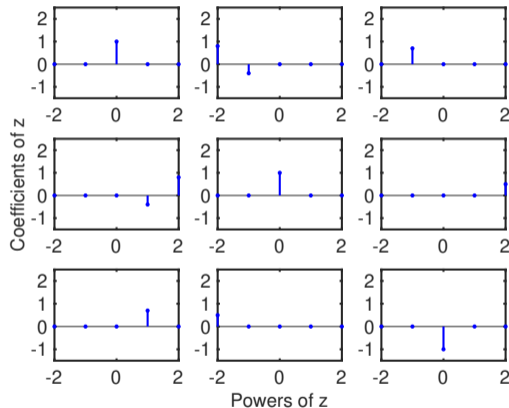


Matrix with polynomial elements.

What Is A Polynomial Matrix?

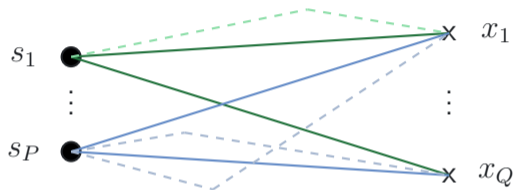


Polynomial with matrix coefficients.



Matrix with polynomial elements.

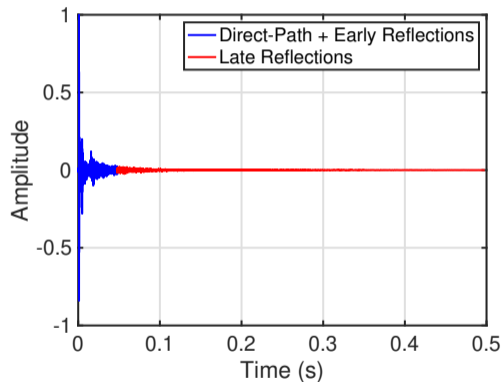
Consider the following MIMO system.



- Source signals: s_1, \dots, s_P
- Received signals: x_1, \dots, x_Q
- Multi-paths with different delays \Rightarrow convolutive mixtures (polynomials in z)
- $h_{p,q}$: channel from p th source to q th sensor, J -th order FIR filter

Figure is taken from the DREAMS project on the Imperial SAP website.

The q -th channel modelled as a FIR filter: $\mathbf{h}_q = \mathbf{h}_{q,dp} + \mathbf{h}_{q,er} + \mathbf{h}_{q,lr}$



An example of a room impulse response.

For a single speaker, the received signal at the q -th sensor with time index n is

$$x_q(n) = \mathbf{h}_q^T \mathbf{s}_0(n) + v_q(n) = \tilde{s}_q(n) + \tilde{v}_q(n)$$

where

- $\tilde{s}_q(n)$ is the speech associated with the direct-path and early reflections,
- $\tilde{v}_q(n)$ is the noise and late reflections,
- $\mathbf{s}_0(n)$ is the anechoic speech signal,
- $v_q(n)$ is the noise signal at the q -th sensor.

The data vector collected from Q sensors is

$$\mathbf{x}(n) = [x_1(n), x_2(n), \dots, x_Q(n)]^T \in \mathbb{R}^Q.$$

Assuming stationarity, the space-time covariance matrix is

$$\mathbf{R}_{\mathbf{xx}}(\tau) = \mathbb{E}[\mathbf{x}(n)\mathbf{x}^H(n - \tau)]$$

where $(i, j)^{\text{th}}$ element is the correlation function $r_{ij}(\tau) = \mathbb{E}[x_i(n)x_j(n - \tau)]$ and τ is the time-shift.

Instantaneous spatial covariance matrix: $\mathbf{R}_{\mathbf{xx}}(0) = \mathbb{E}[\mathbf{x}(n)\mathbf{x}^H(n)]$ using $\tau = 0$.

The z -transform denoted by $\mathbf{R}_{\mathbf{xx}}(\tau) \circ \bullet \mathcal{R}_{\mathbf{xx}}(z)$ is a para-Hermitian polynomial matrix

$$\mathcal{R}_{\mathbf{xx}}(z) = \sum_{\tau=-W}^W \mathbf{R}_{\mathbf{xx}}(\tau)z^{-\tau},$$

where $\mathbf{R}_{\mathbf{xx}}(\tau) \approx 0$ for $|\tau| > W$, calligraphy \mathcal{R} for tensor and regular \mathbf{R} for matrix.

PEVD of $\mathcal{R}_{\mathbf{xx}}(z)$ is defined as [McWhirter2007; Redif2015; Neo2019b; Weiss2018]

$$\mathcal{R}_{\mathbf{xx}}(z) \approx \mathbf{U}(z)\mathbf{\Lambda}(z)\mathbf{U}^P(z) \Leftrightarrow \mathbf{\Lambda}(z) \approx \mathbf{U}^P(z)\mathcal{R}_{\mathbf{xx}}(z)\mathbf{U}(z),$$

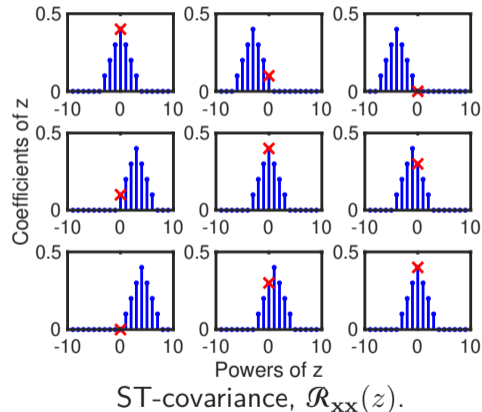
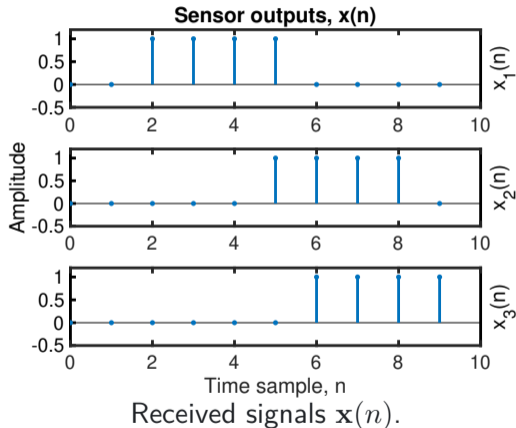
where $\mathbf{\Lambda}(z)$, $\mathbf{U}(z) \bullet \rightarrow \mathbf{U}(n)$ are the eigenvalue, eigenvector polynomial matrices respectively, $\mathcal{R}_{\mathbf{xx}}^P(z) = \mathcal{R}_{\mathbf{xx}}^H(1/z^*)$, and signals $\mathbf{y}(n) = \sum_{\nu} \mathbf{U}^H(-\nu)\mathbf{x}(n - \nu)$ are strongly decorrelated.

EVD of $\mathbf{R}_{\mathbf{xx}}(0)$, the matrix coefficient of z^0 , is:

$$\mathbf{R}_{\mathbf{xx}}(0) = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^H \Leftrightarrow \mathbf{\Lambda} = \mathbf{U}^H\mathbf{R}_{\mathbf{xx}}(0)\mathbf{U} = \mathbb{E}\{\mathbf{y}(n)\mathbf{y}^H(n)\},$$

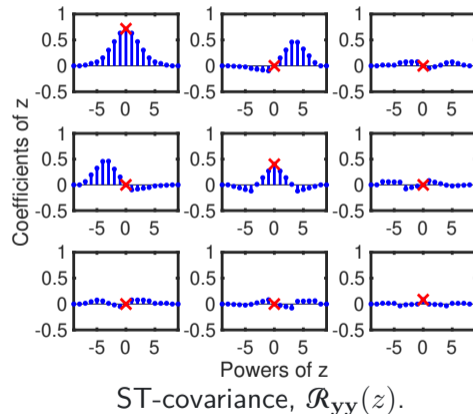
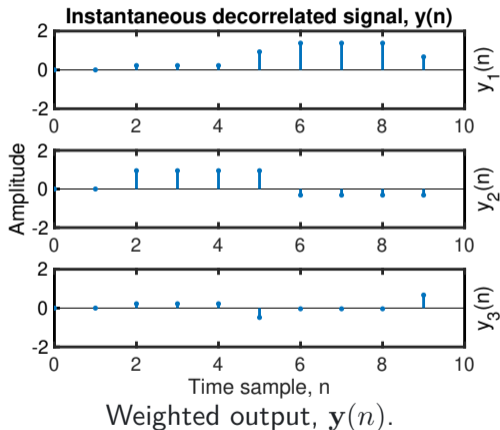
where signals $\mathbf{y}(n) = \mathbf{U}^H\mathbf{x}(n)$ are instantaneously decorrelated.

Example: rectangular source arriving at the 3 sensors

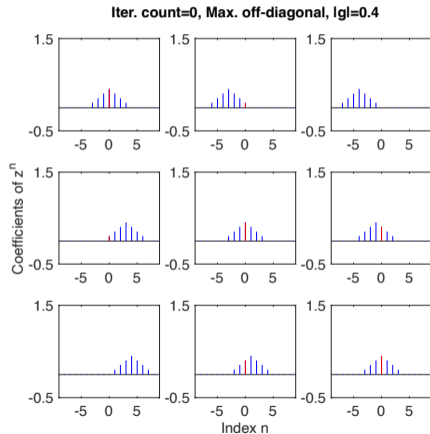


- instantaneous covariance marked by red crosses

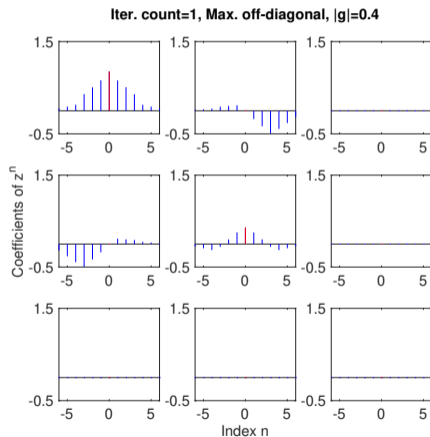
Using \mathbf{U} from EVD gives $\mathbf{y}(n)$ and its $\mathcal{R}_{\mathbf{y}\mathbf{y}}(z)$:



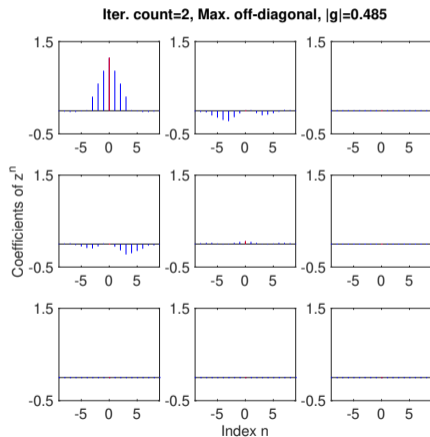
Performing PEVD using SMD: $\delta = 0.010$, $\mu = 10^{-4}$, $L = 500$ gives



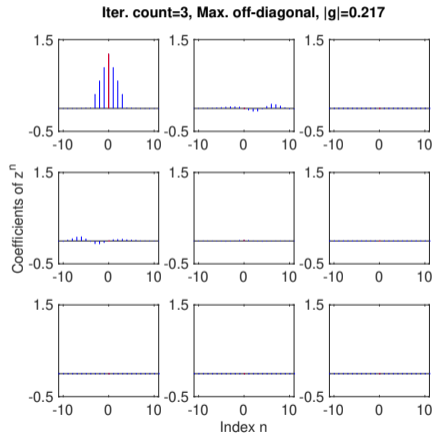
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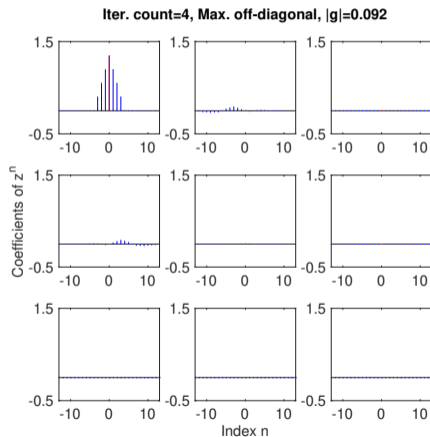
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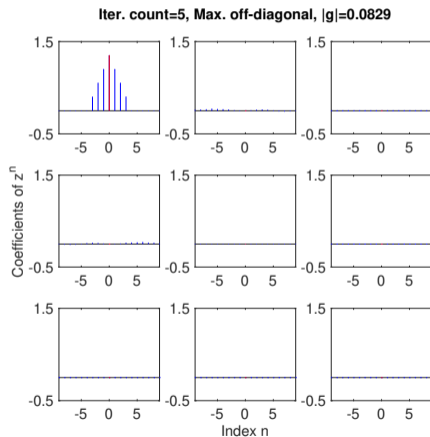
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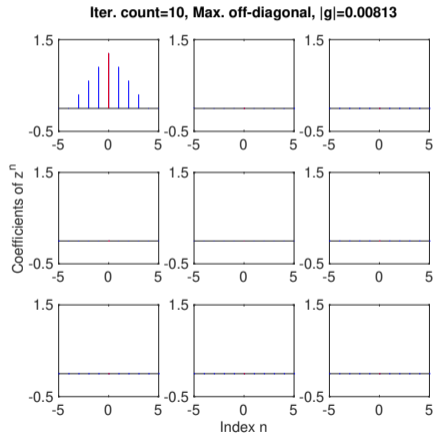
Performing PEVD using SMD: $\delta = 0.010$, $\mu = 10^{-4}$, $L = 500$ gives



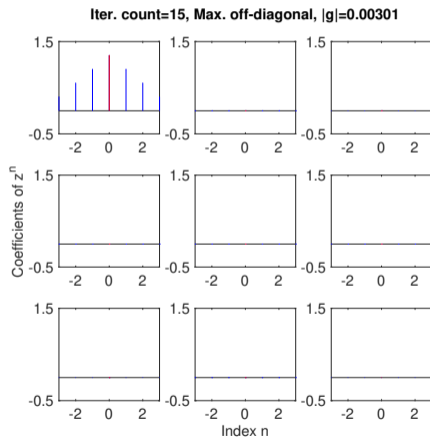
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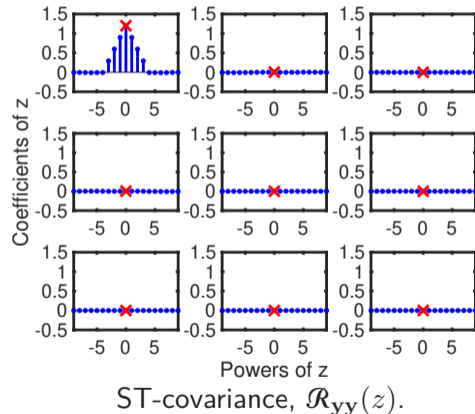
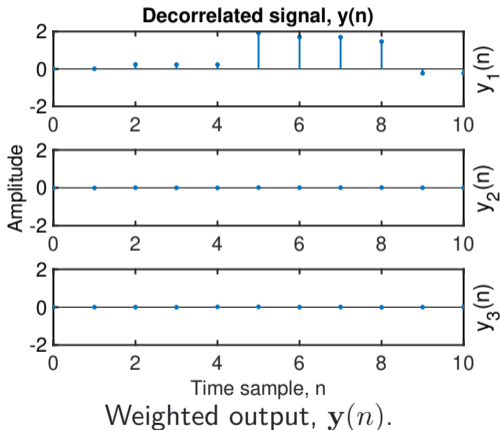
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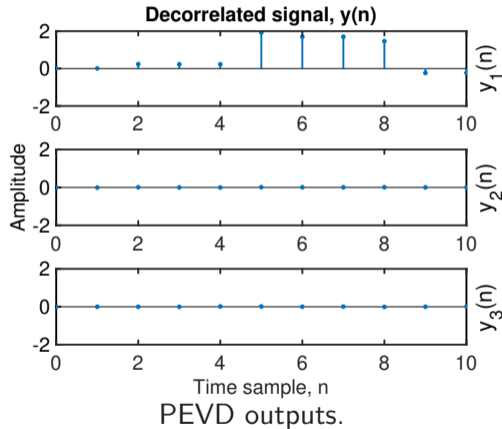
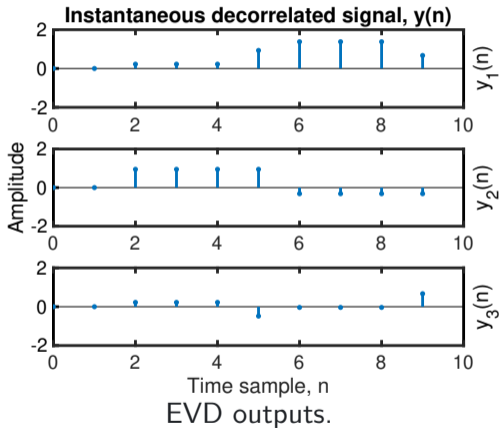
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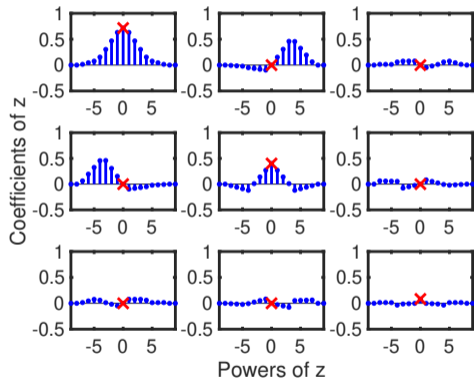
Using $\mathbf{U}(z)$ from PEVD gives $\mathbf{y}(n)$ and its $\mathcal{R}_{\mathbf{y}\mathbf{y}}(z)$:



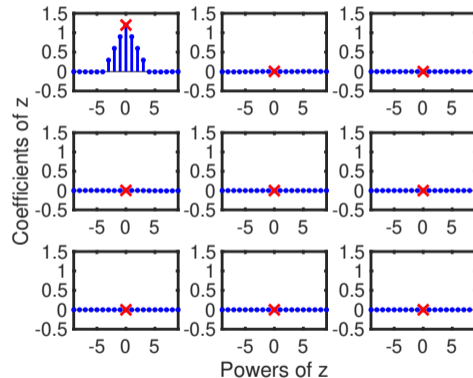
Output signals are:



Space-time covariance matrix of the outputs:



Space-time covariance of EVD output.



Space-time covariance of PEVD output.

For the rectangular signal example,

- EVD: only decorrelate instantaneously \rightarrow cannot recover rectangular
- PEVD: impose (strong) decorrelation over time shifts \rightarrow recover rectangular

Interpretation

- EVD: Any function = linear combination of the bases
- PEVD: Any function = linear combination of the bases and its shifted versions

\Rightarrow PEVD uses fewer number of basis for the same representation as EVD

\Rightarrow PEVD achieves greater compression with fewer components

Key Ingredients: (i) Space-time Covariance Matrix; (ii) Strong decorrelation property of PEVD; (iii) Broadband steering vector

I Enhancement of Noisy Reverberant Speech

V. W. Neo, C. Evers, and P. A. Naylor, "Enhancement of noisy reverberant speech using polynomial matrix eigenvalue decomposition", in: *IEEE/ACM Trans. Audio, Speech, Lang. Process.*, 29, pp.3255-3266, Oct 2021.

II Signal Compaction for Spherical Microphone Array Processing

V. W. Neo, C. Evers, S. Weiss, and P. A. Naylor, "Signal compaction using polynomial EVD for spherical array processing with applications", in: *IEEE/ACM Trans. Audio, Speech, Lang. Process.*, to appear.

III Fixed Beamformer Design Using PEVD

V. W. Neo, E. d'Olne, A. H. Moore, and P. A. Naylor, "Fixed beamformer design using polynomial eigenvalue decomposition", in: *Proc. Intl. Workshop on Acoustic Signal Enhancement (IWAENC)*, pp.1-5, Sep 2022.

Application I. Enhancement of Noisy Reverberant Speech

The subspace decomposed by PEVD gives

$$\mathcal{R}_{\mathbf{x}\mathbf{x}}(z) = \left[\mathbf{u}_s(z) \mid \mathbf{u}_v(z) \right] \left[\begin{array}{c|c} \mathbf{\Lambda}_s(z) & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{\Lambda}_v(z) \end{array} \right] \left[\begin{array}{c} \mathbf{u}_s^P(z) \\ \mathbf{u}_v^P(z) \end{array} \right],$$

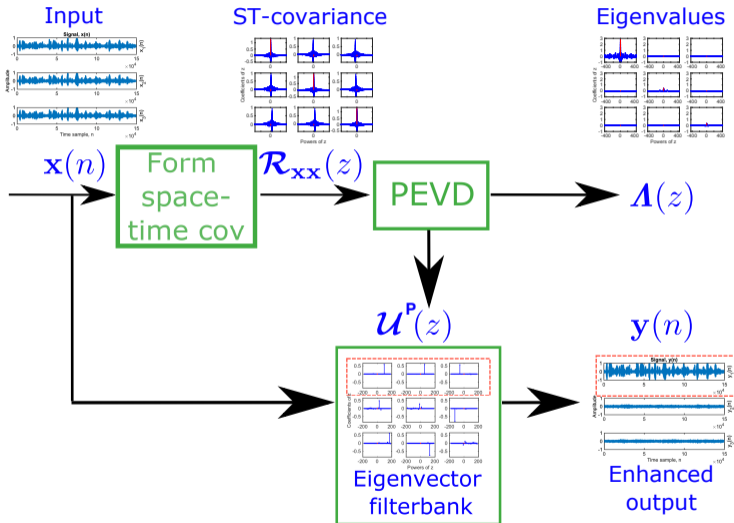
with orthogonal signal, $\{\cdot\}_s$ and noise subspaces, $\{\cdot\}_v$.

The strongly decorrelated output generated using $\mathbf{U}(z) \bullet \circ \mathbf{U}(n)$

$$\mathbf{y}(n) = \sum_{\nu} \mathbf{U}^H(-\nu) \mathbf{x}(n - \nu),$$

has the first element, $y_1(n)$, as the denoised and enhanced speech signal with the space-time covariance matrix

$$\mathcal{R}_{\mathbf{y}\mathbf{y}} = \left[\mathbf{u}_s(z) \mid \mathbf{0} \right] \left[\begin{array}{c|c} \mathbf{\Lambda}_s(z) & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{0} \end{array} \right] \left[\begin{array}{c} \mathbf{u}_s^P(z) \\ \mathbf{0} \end{array} \right].$$



⇒ Achieves significant

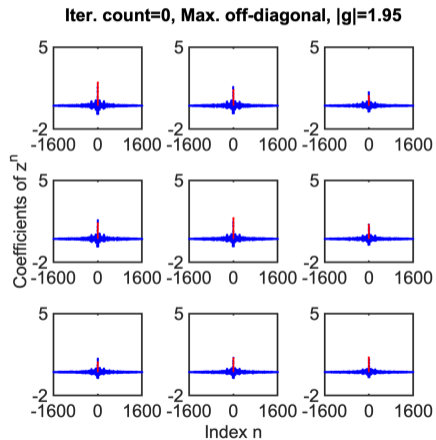
- noise reduction
- dereverberation
- speech enhancement

⇒ Arbitrary arrays

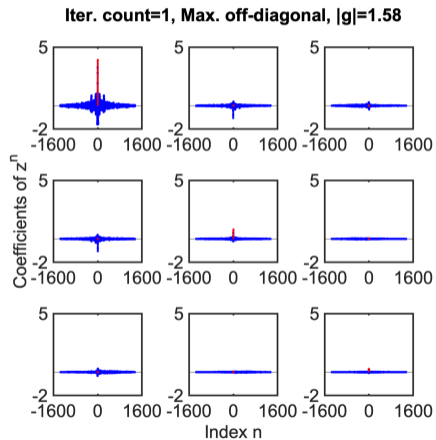
⇒ No noise estimation

⇒ No noticeable processing artefacts

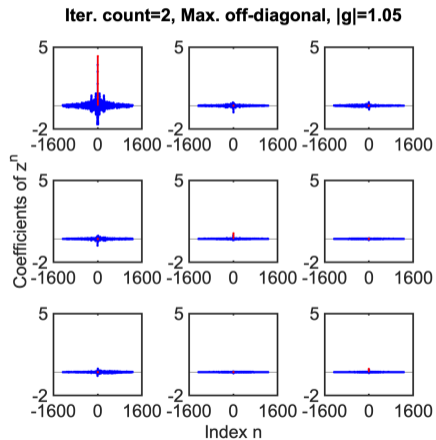
Algorithm converges when $|g| < 1.68 \times 10^{-2}$



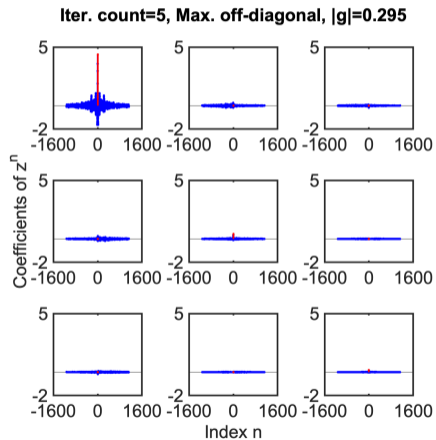
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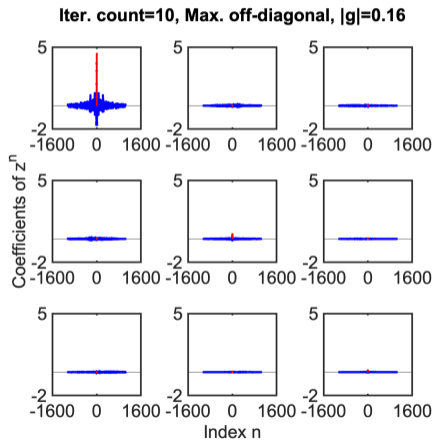
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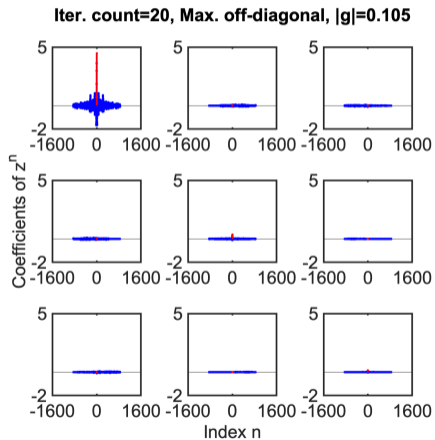
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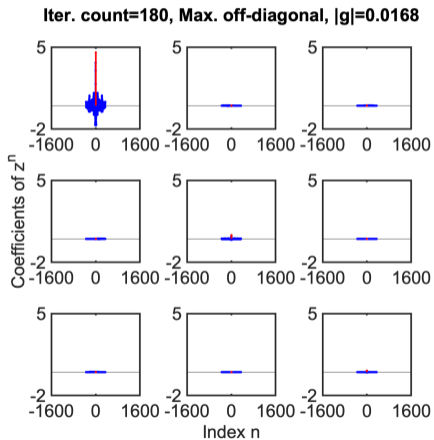
Algorithm converges when $|g| < 1.68 \times 10^{-2}$



Algorithm converges when $|g| < 1.68 \times 10^{-2}$



Algorithm converges when $|g| < 1.68 \times 10^{-2}$



| <i>Algorithm</i> | Δ SegSNR | Δ FwSegSNR | Δ STOI | Δ PESQ |
|------------------|-----------------|-------------------|---------------|---------------|
| COLSUB | 8.35 dB | 7.67 dB | -0.018 | -0.20 |
| log-MMSE | 3.67 dB | 3.05 dB | -0.058 | -0.12 |
| MCSUB | -1.52 dB | -1.04 dB | -0.010 | -0.03 |
| MWF | 1.06 dB | 0.78 dB | -0.005 | 0.02 |
| OMWF | 0.57 dB | -0.44 dB | 0.084 | 0.17 |
| PEVD | 2.96 dB | 2.88 dB | 0.078 | 0.11 |



Listening Examples: <https://vwn09.github.io/pevd-enhance/>

Application II. Signal Compaction for Spherical Microphone Arrays

- PEVD-based speech enhancement [Neo2019a; Neo2020; Neo2021]
 - Use PEVD to impose spatial decorrelation over a range of time shifts
 - Effective for noise reduction and dereverberation
 - Robust for linear and arbitrary array geometries
 - Works well for distributed arrays [d'Oln2022]

⇒ Limitation: Complexity at best \propto (# of signals for processing)³

Can we exploit known information such as array geometry?

Focus: Spherical Microphone Array due to its relevance in hearing aids, sound field decomposition and reproduction, robot audition

The ℓ -th order, m -th degree eigenbeam signal, associated with the real SH basis function $\Upsilon_{\ell}^m(\mathbf{r}_q)$ and quadrature sampling weight α_q , is

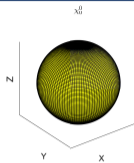
$$\chi_{\ell}^m(n) \approx \sum_{q=1}^Q \alpha_q x(n, \mathbf{r}_q) \Upsilon_{\ell}^m(\mathbf{r}_q).$$

Recovery of the microphone signal at spherical coordinate \mathbf{r}_q uses a weighted sum of the SH

$$x(n, \mathbf{r}_q) = \sum_{\ell=0}^L \sum_{m=-\ell}^{\ell} \chi_{\ell}^m(n) \Upsilon_{\ell}^m(\mathbf{r}_q)$$

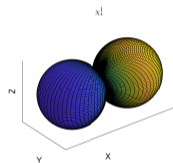
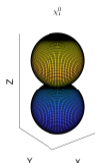
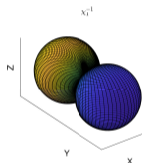
and alias-free spatial reconstruction requires $Q \geq (L + 1)^2$ where L is the maximum SH order of the sound field and $\mathcal{L} \triangleq (L + 1)^2$ eigenbeams.

$$l = 0$$

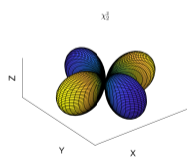
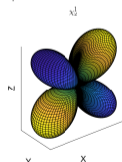
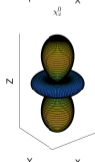
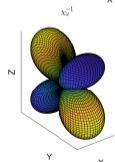
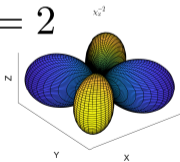


$$\mathcal{L} = (L + 1)^2$$

$$l = 1$$



$$l = 2$$



$$m = -2$$

$$m = -1$$

$$m = 0$$

$$m = 1$$

$$m = 2$$

ACE Lecture Room 2 with 10 dB Babble Noise

| | | | | | |
|----------------------------------|------|-------|-------|-------|-------|
| SH Order, L | 0 | 1 | 2 | 3 | 4 |
| # Eigenbeams \mathcal{L} | 1 | 4 | 9 | 16 | 25 |
| Approx. Error, $\varepsilon(\%)$ | 31.7 | 13.3 | 8.4 | 5.4 | 2.3 |
| Complexity Factor, β | - | 0.002 | 0.022 | 0.125 | 0.477 |

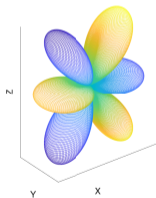
* $\beta = (\frac{\mathcal{L}}{Q})^3$, where $Q = 32$ microphones.

⇒ A small number of eigenbeams (of a sufficiently large SH order) can sufficiently represent the microphone signals. This compact signal representation can reduce the number of signals used for PEVD processing.

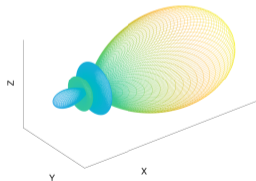
Given target source DoA (θ_p, ϕ_p) , eigenbeam signals $\chi_\ell^m(n)$ are steered or used to form P beamformer outputs $\psi(n) = [\psi_1(n), \dots, \psi_P(n)]^T$.

If w_ℓ^m represents modal beamformer weight or $\{0, 1\}$ for eigenbeam selection

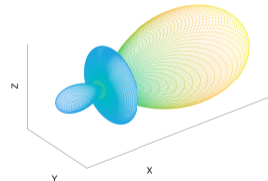
$$\psi_p(n) = \sum_{\ell=0}^L \sum_{m=-\ell}^{\ell} w_\ell^m \chi_\ell^m(n)$$



Steered eigenbeam.



Maximum directivity index
(MaxDir) beamformer.



Modified hyper-cardioid
(MHCARD) beamformer.

Assuming stationarity, the space-time covariance matrix of P modal outputs is

$$\mathbf{R}_{\psi\psi}(\tau) = \mathbb{E}[\boldsymbol{\psi}(n)\boldsymbol{\psi}^T(n - \tau)],$$

where $(i, j)^{\text{th}}$ element is the correlation function $r_{ij}(\tau) = \mathbb{E}[\psi_i(n)\psi_j(n - \tau)]$ and τ is the time-shift.

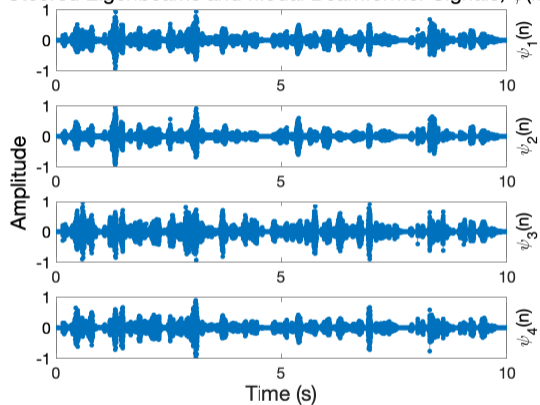
Z-transform of $\mathbf{R}_{\psi\psi}(\tau)$ is a para-Hermitian polynomial matrix

$$\mathcal{R}_{\psi\psi}(z) = \sum_{\tau=-W}^W \mathbf{R}_{\psi\psi}(\tau)z^{-\tau},$$

where $\mathbf{R}_{\psi\psi}(\tau) \approx 0$ for $|\tau| > W$, calligraphic \mathcal{R} for polynomial matrices and regular \mathbf{R} for matrices.

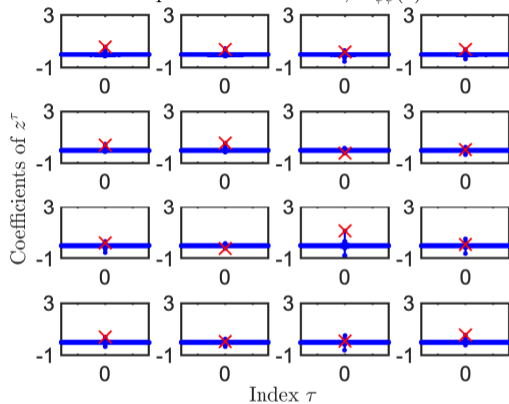
Example: Polynomial Matrix from ST-Covariance

Steered Eigenbeams and Modal Beamformer Signals, $\psi(n)$



Modal signals $\psi(n)$.

Space-time covariance, $\mathcal{R}_{\psi\psi}(z)$



Polynomial matrix, $\mathcal{R}_{\psi\psi}(z)$.

The PEVD of $\mathcal{R}_{\psi\psi}(z)$ is [McWhirter2007]

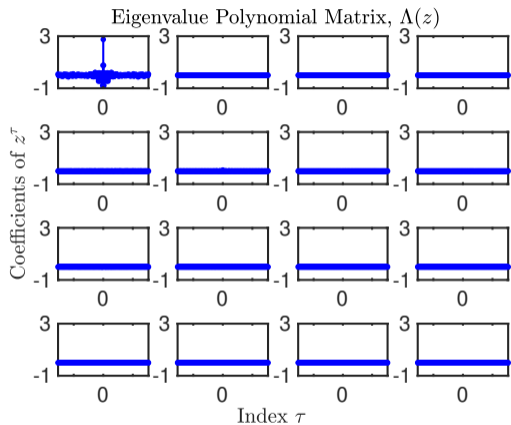
$$\mathcal{R}_{\psi\psi}(z) \approx \mathbf{U}^P(z) \mathbf{\Lambda}(z) \mathbf{U}(z),$$

where $\mathbf{\Lambda}(z)$, $\mathbf{U}(z)$ contain the eigenvalues and eigenvectors and $\mathcal{R}_{\psi\psi}^P(z) = \mathcal{R}_{\psi\psi}^H(1/z^*)$.

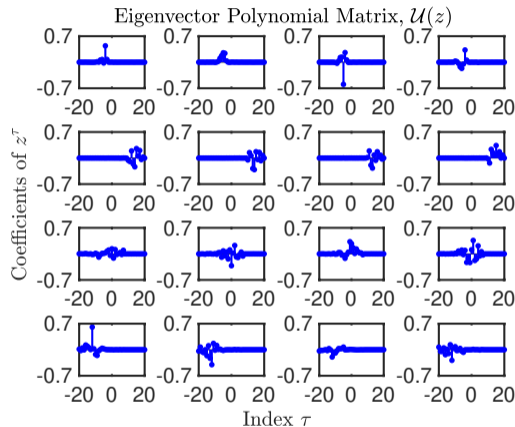
Subspace decomposition by the PEVD generates strongly decorrelated outputs:

$$\mathcal{R}_{\psi\psi}(z) = \left[\mathbf{u}_s^P(z) \mid \mathbf{u}_{s^\perp}^P(z) \right] \left[\begin{array}{c|c} \mathbf{\Lambda}_s(z) & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{\Lambda}_{s^\perp}(z) \end{array} \right] \left[\begin{array}{c} \mathbf{u}_s(z) \\ \mathbf{u}_{s^\perp}(z) \end{array} \right],$$

associated with orthogonal target source, $\{\cdot\}_s$ and interferer, $\{\cdot\}_{s^\perp}$ subspaces.

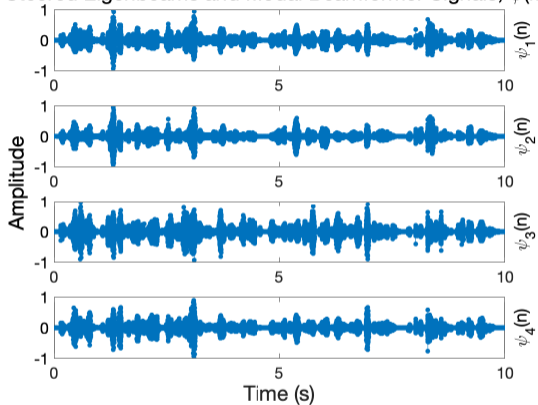


Eigenvalue polynomial matrix, $\Lambda(z)$.



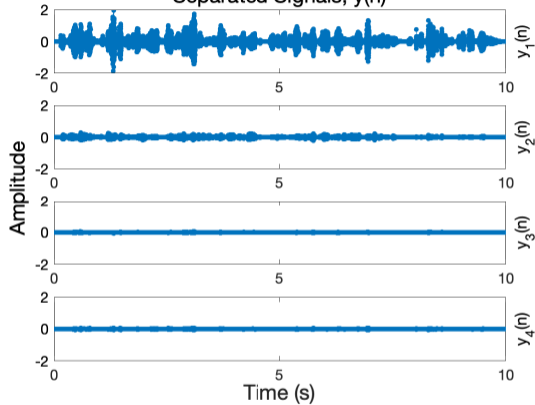
Eigenvector polynomial matrix, $\mathcal{U}(z)$.

Steered Eigenbeams and Modal Beamformer Signals, $\psi(n)$

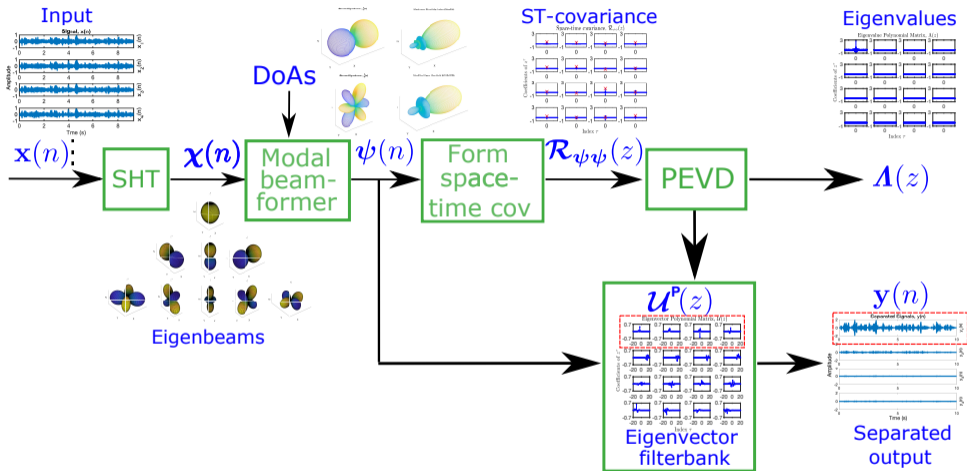


Modal signals $\psi(n)$.

Separated Signals, $y(n)$



Extracted source signals, $y(n)$.



⇒ SHT+PEVD: close to optimum signal compaction at reduced complexity while achieving good informed source separation and blind speech enhancement performance.

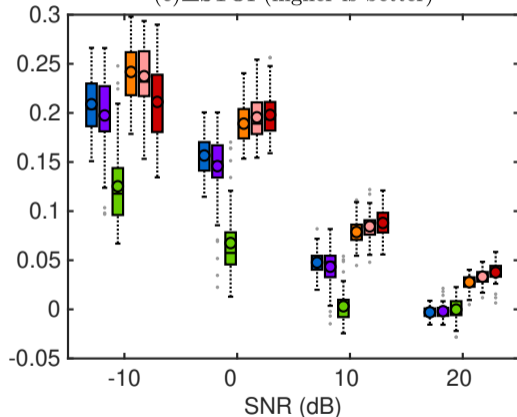
| <i>Algorithm</i> | Δ SDR | Δ SIR | Δ SAR | Δ STOI | Δ PESQ |
|------------------|----------------|----------------|----------------|---------------|---------------|
| AuxIVA | 17.7 dB | 25.3 dB | 11.4 dB | 0.21 | 1.05 |
| FastMNMF | 20.6 dB | 35.2 dB | 13.8 dB | 0.21 | 1.28 |
| ILRMA | 19.5 dB | 31.3 dB | 12.8 dB | 0.21 | 1.21 |
| MaxDir | 3.9 dB | 3.4 dB | 4.7 dB | 0.07 | 0.22 |
| PEVD | 21.8 dB | 25.3 dB | 16.4 dB | 0.24 | 1.39 |



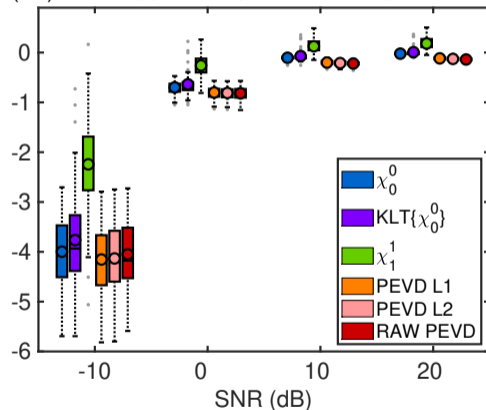
Listening Examples: <https://vwn09.github.io/pevd-smap/>

Condition: ACE Lecture Room 2, Babble Noise

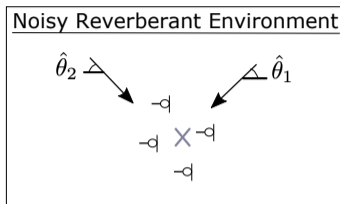
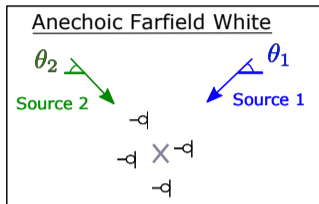
(c) Δ STOI (higher is better)



(f) Δ BSD (lower is better)

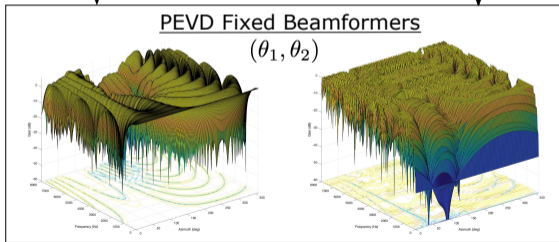


Application III. Fixed Beamformer Design Using PEVD



Training

Testing $(\hat{\theta}_1, \hat{\theta}_2)$



- ⇒ PEVD eigenvectors interpreted as beamformers
- ⇒ Arbitrary arrays
- ⇒ Avg. filter length: 114
- ⇒ Source separation performance approach data-dependent MVDR and LCMV beamformers

Rewriting as $\mathbf{H}(n) \circ \bullet \mathcal{H}(z) \in \mathbb{C}^{P \times Q}$, where each element is $h_{p,q}(n)$:

$$\mathbf{R}_x(z) = \mathcal{H}^P(z) \mathbf{R}_s(z) \mathcal{H}(z) + \sigma_v^2 \mathbf{I},$$

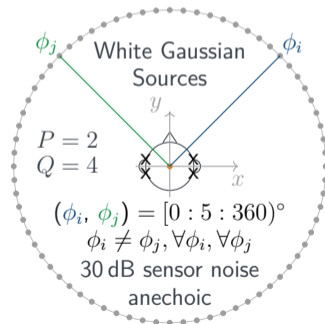
with spatially and temporally white noise $\mathbf{v}(n)$ of equal power σ_v^2 .

With i.i.d. source signals and each drawn from $N(0, 1)$, $\mathbf{R}_s(z) = \mathbf{I} \in \mathbb{C}^{P \times P}$.

Applying PEVD and rearranging:

$$\mathbf{\Lambda}(z) - \sigma_v^2 \mathbf{I} = \mathbf{U}^P(z) \mathcal{H}^P(z) \mathcal{H}(z) \mathbf{U}(z).$$

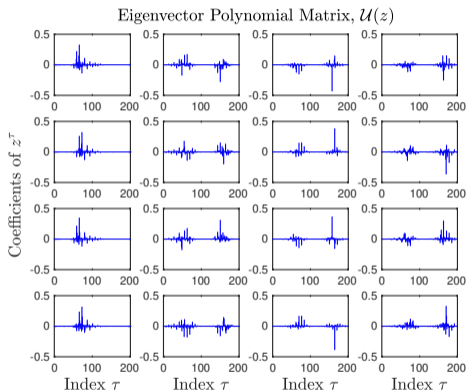
Training Using Simulated
Impulse Responses



Diagonalization $\implies \mathbf{u}(z)$ spatially decorrelate the acoustic channels $\mathcal{H}(z)$.
By evaluating on the unit circle, beampattern response at frequency Ω :

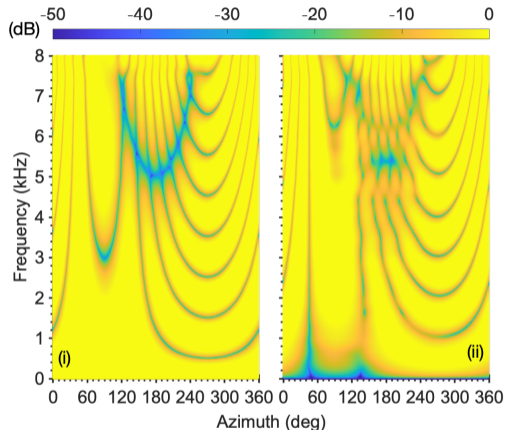
$$\mathbf{B}(\phi, \Omega) = [\mathbf{u}^P(z)\mathbf{a}_\phi(z)] \Big|_{z=e^{j\Omega}},$$

where $\mathbf{a}_\phi(n) \rightsquigarrow \mathbf{a}_\phi(z) \in \mathbb{C}^Q$ is the broadband steering vector using array geometry and the q th element is $a_q(n) = \text{sinc}(nT_s - \Delta\tau_q)$ with sampling period T_s and relative time delay $\Delta\tau_q$.



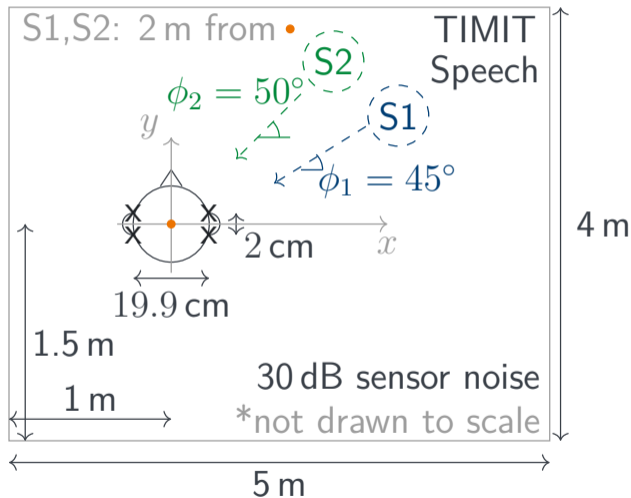
PEVD filterbank for $\{45^\circ, 50^\circ\}$

⇒ Since each element is a FIR filter, each PEVD eigenvector can be interpreted as a filterbank.



PEVD beamformer for $\{45^\circ, 50^\circ\}$

Testing Setup For Separation of Two Speakers



| Algorithm | S1 ($\phi_1 = 45^\circ$) | | S2 ($\phi_2 = 50^\circ$) | |
|-----------------|----------------------------|-------------------|----------------------------|---------------|
| | Δ STOI | Δ SIR (dB) | Δ STOI | SIR (dB) |
| PEVD {45°, 50°} | 0.002 | -0.034 | 0.204 | 15.752 |
| PEVD {50°, 45°} | 0.123 | 16.703 | 0.004 | 0.247 |
| MVDR | 0.113 | 13.487 | 0.186 | 12.435 |
| LCMV | 0.047 | 19.986 | 0.156 | 23.522 |

⇒ First PEVD output is similar to delay-and-sum that maximizes correlation in the look direction

⇒ Orthogonality across range of time lags as enforced by PEVD places a deep null in the first look direction in the Second PEVD output

Listening Examples:

<https://vwn09.github.io/research/pevd-beamformer-iwaenc>








PEVD has also been used for other speech processing applications

- Distributed array processing [d'Olne2022]
- Voice activity detection [Neo2022c; Neo2022b]
- Sound source localization [Hogg2021]

Conclusions

- Polynomial matrices are suited for modelling multichannel broadband signals e.g. speech
- PEVD achieves diagonalization of the space-time covariance over a range of time lags vs instantaneous spatial covariance for a single lag using EVD
- PEVD provides a more compact signal representation using fewer components compared to EVD
- Strong decorrelation and orthogonalizing properties of PEVD are useful for a variety of applications including speech enhancement, signal compaction, source separation and beamformer design

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Thank you



Enhancement



Spherical



Beamformer